

## Exercise 2

Use the same vector field to evaluate both sides of Eq. A.5-4 for the face  $x_1 = 1$  in Exercise 1.

### Solution

Eq. A.5-4 states Stokes's theorem,

$$\iint_S (\hat{\mathbf{n}} \cdot [\nabla \times \mathbf{v}]) dS = \oint_C (\hat{\mathbf{t}} \cdot \mathbf{v}) dC,$$

where  $\hat{\mathbf{t}}$  is a unit vector tangent to the integration path  $C$  and  $\hat{\mathbf{n}}$  is a unit vector in the direction the thumb points when the fingers of the right hand curl in the direction of the path. From Exercise 1, we have

$$\mathbf{v} = \delta_1 x_1 + \delta_2 x_3 + \delta_3 x_2.$$

### The Left-hand Side

To evaluate the left-hand side, determine the curl of  $\mathbf{v}$ .

$$\nabla \times \mathbf{v} = \begin{vmatrix} \delta_1 & \delta_2 & \delta_3 \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ x_1 & x_3 & x_2 \end{vmatrix} = \mathbf{0}$$

As a result, the left-hand side is zero.

$$\begin{aligned} \iint_S (\hat{\mathbf{n}} \cdot [\nabla \times \mathbf{v}]) dS &= \iint_S (\hat{\mathbf{n}} \cdot \mathbf{0}) dS \\ &= 0 \end{aligned}$$

### The Right-hand Side

The boundary of the  $x_1 = 1$  face is made up of four paths as shown in the figure, so the closed loop integral splits up into four single integrals.

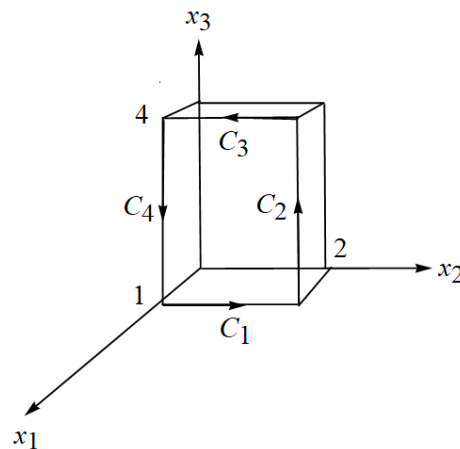


Figure 1: Schematic of the  $x_1 = 1$  face and the integration path around its boundary.

$$\oint_C (\hat{\mathbf{t}} \cdot \mathbf{v}) dC = \int_{C_1} (\hat{\mathbf{t}} \cdot \mathbf{v}) dC + \int_{C_2} (\hat{\mathbf{t}} \cdot \mathbf{v}) dC + \int_{C_3} (\hat{\mathbf{t}} \cdot \mathbf{v}) dC + \int_{C_4} (\hat{\mathbf{t}} \cdot \mathbf{v}) dC$$

The tangent vector along  $C_1$  is  $\delta_2$ , the tangent vector along  $C_2$  is  $\delta_3$ , the tangent vector along  $C_3$  is  $-\delta_2$ , and the tangent vector along  $C_4$  is  $-\delta_3$ .

$$\begin{aligned} \oint_C (\hat{\mathbf{t}} \cdot \mathbf{v}) dC &= \int_{C_1} \delta_2 \cdot (\delta_1 x_1 + \delta_2 x_3 + \delta_3 x_2) dC + \int_{C_2} \delta_3 \cdot (\delta_1 x_1 + \delta_2 x_3 + \delta_3 x_2) dC \\ &\quad + \int_{C_3} (-\delta_2) \cdot (\delta_1 x_1 + \delta_2 x_3 + \delta_3 x_2) dC + \int_{C_4} (-\delta_3) \cdot (\delta_1 x_1 + \delta_2 x_3 + \delta_3 x_2) dC \end{aligned}$$

Evaluate the dot products.

$$\oint_C (\hat{\mathbf{t}} \cdot \mathbf{v}) dC = \int_{C_1} x_3 dC + \int_{C_2} x_2 dC + \int_{C_3} (-x_3) dC + \int_{C_4} (-x_2) dC$$

Along the  $C_1$  path,  $x_3 = 0$ ; along the  $C_2$  path,  $x_2 = 2$ ; along the  $C_3$  path,  $x_3 = 4$ ; and along the  $C_4$  path,  $x_2 = 0$ .

$$\oint_C (\hat{\mathbf{t}} \cdot \mathbf{v}) dC = \int_{C_1} 0 dC + \int_{C_2} 2 dC + \int_{C_3} (-4) dC + \int_{C_4} (-0) dC$$

Bring the constants in front of the nonzero integrals.

$$\oint_C (\hat{\mathbf{t}} \cdot \mathbf{v}) dC = 2 \int_{C_2} dC - 4 \int_{C_3} dC$$

The length of the  $C_2$  path is 4, and the length of the  $C_3$  path is 2. Therefore,

$$\begin{aligned} \oint_C (\hat{\mathbf{t}} \cdot \mathbf{v}) dC &= 2(4) - 4(2) \\ &= 0. \end{aligned}$$

We conclude that Stokes's theorem is verified.