

## Problem 2B.4

**Laminar slit flow with a moving wall** (“plane Couette flow”). Extend Problem 2B.3 by allowing the wall at  $x = B$  to move in the positive  $z$  direction at a steady speed  $v_0$ . Obtain (a) the shear-stress distribution and (b) the velocity distribution. Draw carefully labeled sketches of these functions.

$$\text{Answers: } \tau_{xz} = \left( \frac{\mathcal{P}_0 - \mathcal{P}_L}{L} \right) x - \frac{\mu v_0}{2B}; \quad v_z = \frac{(\mathcal{P}_0 - \mathcal{P}_L)B^2}{2\mu L} \left[ 1 - \left( \frac{x}{B} \right)^2 \right] + \frac{v_0}{2} \left( 1 + \frac{x}{B} \right)$$

### Solution

The analysis in this problem is the same as in Problem 2B.3 except that the boundary conditions are different. Here the velocity at  $x = B$  is equal to  $v_0$ , and the velocity at  $x = -B$  is equal to 0.

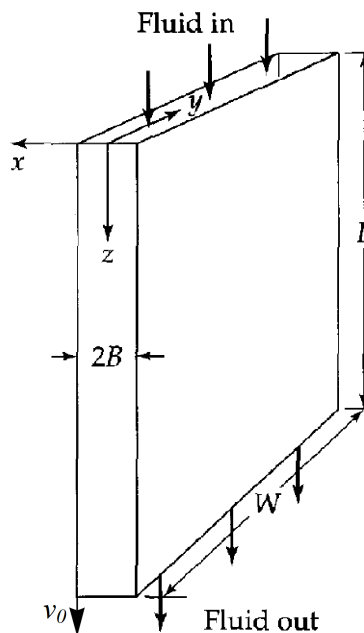


Figure 1: This is Fig. 2B.3 with the wall at  $x = B$  moving in the positive  $z$ -direction with speed  $v_0$ . Fluid is flowing through the slit with  $B \ll W \ll L$ .

We assume that the fluid flows in the  $z$ -direction and that its velocity varies as a function of  $x$ .

$$v_z = v_z(x)$$

As a result, only  $\phi_{xz}$  (the  $z$ -momentum in the positive  $x$ -direction) and  $\phi_{zz}$  (the  $z$ -momentum in the positive  $z$ -direction) contribute to the momentum balance. Also, the boundary conditions are as follows.

$$\text{B.C. 1: } v_z = 0 \quad \text{when } x = -B$$

$$\text{B.C. 2: } v_z = v_0 \quad \text{when } x = B.$$

We also assume the pressure varies with height.

$$p = p(z)$$

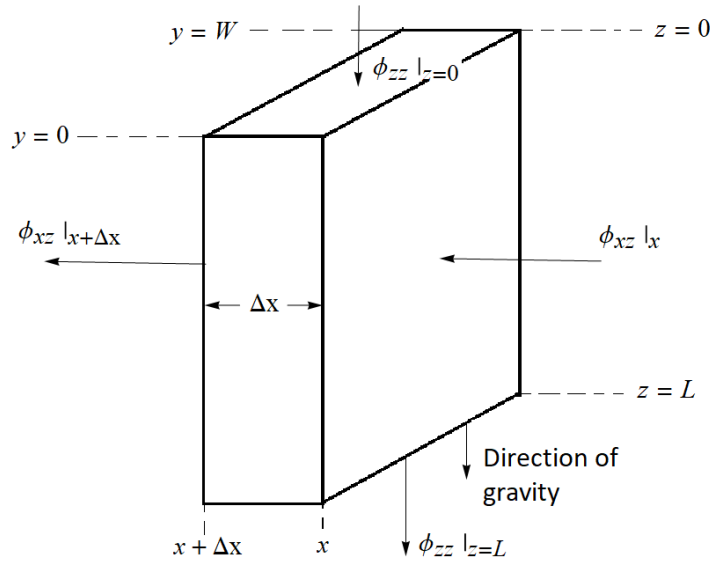


Figure 2: This is the shell over which the momentum balance is made for the flow in a slit.

Rate of $z$ -momentum into the shell at $z = 0$ :	$(W \Delta x) \phi_{zz} _{z=0}$
Rate of $z$ -momentum out of the shell at $z = L$ :	$(W \Delta x) \phi_{zz} _{z=L}$
Rate of $z$ -momentum into the shell at $x$ :	$(WL) \phi_{xz} _x$
Rate of $z$ -momentum out of the shell at $x + \Delta x$ :	$(WL) \phi_{xz} _{x+\Delta x}$
Component of gravitational force on the shell in $z$ -direction:	$(WL \Delta x) \rho g$

If we assume steady flow, then the momentum balance is

$$\text{Rate of momentum in} - \text{Rate of momentum out} + \text{Force of gravity} = 0.$$

Considering only the  $z$ -component, we have

$$(W \Delta x) \phi_{zz}|_{z=0} - (W \Delta x) \phi_{zz}|_{z=L} + (WL) \phi_{xz}|_x - (WL) \phi_{xz}|_{x+\Delta x} + (WL \Delta x) \rho g = 0.$$

Factor the left side.

$$W \Delta x (\phi_{zz}|_{z=0} - \phi_{zz}|_{z=L}) - WL (\phi_{xz}|_{x+\Delta x} - \phi_{xz}|_x) + (WL \Delta x) \rho g = 0$$

Divide both sides by the volume of the shell  $WL \Delta x$ .

$$\frac{\phi_{zz}|_{z=0} - \phi_{zz}|_{z=L}}{L} - \frac{\phi_{xz}|_{x+\Delta x} - \phi_{xz}|_x}{\Delta x} + \rho g = 0$$

Take the limit as  $\Delta x \rightarrow 0$ .

$$\frac{\phi_{zz}|_{z=0} - \phi_{zz}|_{z=L}}{L} - \lim_{\Delta x \rightarrow 0} \frac{\phi_{xz}|_{x+\Delta x} - \phi_{xz}|_x}{\Delta x} + \rho g = 0$$

The second term is the definition of the first derivative.

$$\frac{\phi_{zz}|_{z=0} - \phi_{zz}|_{z=L}}{L} - \frac{d\phi_{xz}}{dx} + \rho g = 0$$

Now substitute the expressions for  $\phi_{xz}$  and  $\phi_{zz}$ .

$$\begin{aligned}\phi_{xz} &= \tau_{xz} + \rho v_x v_z = \tau_{xz} \\ \phi_{zz} &= p\delta_{zz} + \tau_{zz} + \rho v_z v_z = p(z) + \rho v_z^2\end{aligned}$$

Since  $v_z$  does not depend on  $z$ , the  $\rho v_z^2$  terms cancel and we get

$$\frac{p(0) + \rho v_z^2 \Big|_{z=0} - p(L) - \rho v_z^2 \Big|_{z=L}}{L} - \frac{d\tau_{xz}}{dx} + \rho g = 0.$$

Make it so  $\rho g$  is part of the fraction.

$$\frac{p(0) - p(L) + \rho gL}{L} - \frac{d\tau_{xz}}{dx} = 0$$

Subtract  $\rho g0$  from the numerator.

$$\frac{p(0) - \rho g0 - [p(L) - \rho gL]}{L} - \frac{d\tau_{xz}}{dx} = 0$$

Substitute  $\mathcal{P}_z = p(z) - \rho gz$ .

$$\frac{\mathcal{P}_0 - \mathcal{P}_L}{L} - \frac{d\tau_{xz}}{dx} = 0$$

So we have

$$\frac{d\tau_{xz}}{dx} = \frac{\mathcal{P}_0 - \mathcal{P}_L}{L}.$$

From Newton's law of viscosity we know that  $\tau_{xz} = -\mu(dv_z/dx)$ , so

$$\frac{d}{dx} \left( -\mu \frac{dv_z}{dx} \right) = \frac{\mathcal{P}_0 - \mathcal{P}_L}{L}.$$

Bring  $-\mu$  in front of the derivative and then divide both sides by it.

$$\frac{d^2 v_z}{dx^2} = -\frac{\mathcal{P}_0 - \mathcal{P}_L}{\mu L}$$

Integrate both sides of the differential equation with respect to  $x$ .

$$\frac{dv_z}{dx} = -\frac{\mathcal{P}_0 - \mathcal{P}_L}{\mu L} x + C_1$$

Integrate both sides of the differential equation with respect to  $x$  once more.

$$v_z(x) = -\frac{\mathcal{P}_0 - \mathcal{P}_L}{2\mu L} x^2 + C_1 x + C_2$$

Apply the boundary conditions now to determine  $C_1$  and  $C_2$ .

$$v_z(-B) = -\frac{\mathcal{P}_0 - \mathcal{P}_L}{2\mu L} B^2 - C_1 B + C_2 = 0$$

$$v_z(B) = -\frac{\mathcal{P}_0 - \mathcal{P}_L}{2\mu L} B^2 + C_1 B + C_2 = v_0$$

Solving this system of equations for  $C_1$  and  $C_2$  gives

$$C_1 = \frac{v_0}{2B}$$

$$C_2 = \frac{v_0}{2} + \frac{\mathcal{P}_0 - \mathcal{P}_L}{2\mu L} B^2,$$

so we get

$$v_z(x) = -\frac{\mathcal{P}_0 - \mathcal{P}_L}{2\mu L} x^2 + \frac{v_0}{2B} x + \frac{v_0}{2} + \frac{\mathcal{P}_0 - \mathcal{P}_L}{2\mu L} B^2.$$

Factor this result.

$$v_z(x) = \frac{\mathcal{P}_0 - \mathcal{P}_L}{2\mu L} (B^2 - x^2) + \frac{v_0}{2} \left(1 + \frac{x}{B}\right)$$

$$= \frac{\mathcal{P}_0 - \mathcal{P}_L}{2\mu L} B^2 \left(1 - \frac{x^2}{B^2}\right) + \frac{v_0}{2} \left(1 + \frac{x}{B}\right)$$

Therefore,

$$v_z = \frac{(\mathcal{P}_0 - \mathcal{P}_L)B^2}{2\mu L} \left[1 - \left(\frac{x}{B}\right)^2\right] + \frac{v_0}{2} \left(1 + \frac{x}{B}\right).$$

Since  $\tau_{xz} = -\mu(dv_z/dx)$ , we have

$$\tau_{xz} = -\mu \left(-\frac{\mathcal{P}_0 - \mathcal{P}_L}{\mu L} x + \frac{v_0}{2B}\right).$$

Therefore,

$$\tau_{xz} = \frac{\mathcal{P}_0 - \mathcal{P}_L}{L} x - \frac{\mu v_0}{2B}.$$

The maximum velocity can be obtained by taking the derivative of  $v_z(x)$  and setting it equal to zero.

$$\frac{dv_z}{dx} = -\frac{\mathcal{P}_0 - \mathcal{P}_L}{\mu L} x + \frac{v_0}{2B} = 0$$

Solving for  $x$  yields the  $x$ -coordinate where the maximum occurs.

$$x = \frac{\mu L v_0}{2B(\mathcal{P}_0 - \mathcal{P}_L)}$$

Plugging this into  $v_z(x)$  and simplifying, we get

$$v_z \left( \frac{\mu L v_0}{2B(\mathcal{P}_0 - \mathcal{P}_L)} \right) = \frac{[2B^2(\mathcal{P}_0 - \mathcal{P}_L) + \mu L v_0]^2}{8B^2 \mu L (\mathcal{P}_0 - \mathcal{P}_L)}$$

for the maximum velocity.

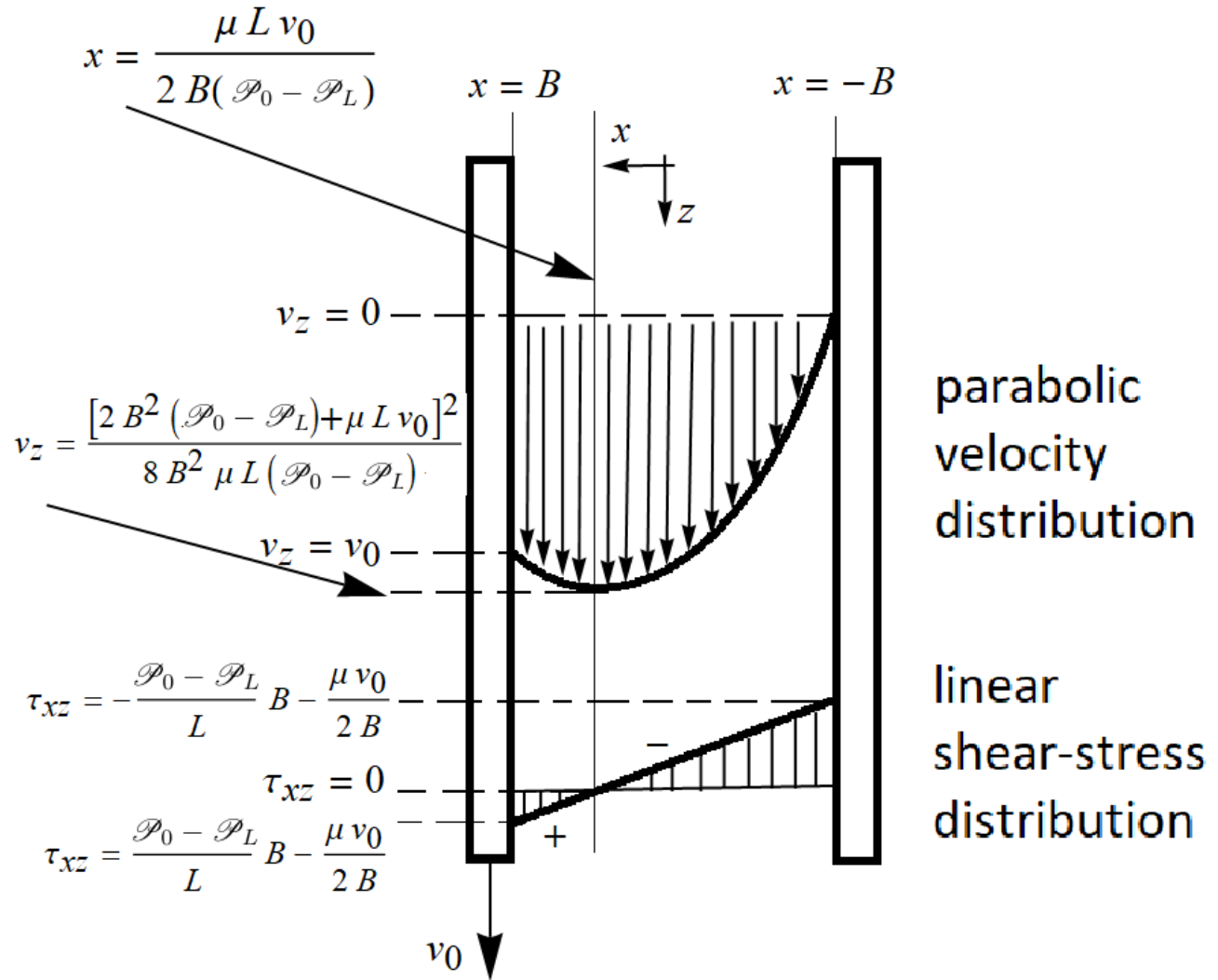


Figure 3: This is a carefully labeled sketch of the velocity distribution  $v_z(x)$  and the shear-stress (momentum-flux) distribution  $\tau_{xz}(x)$  for flow in a slit with one wall moving at speed  $v_0$ .