

Problem 41

In this problem we indicate one way to show that if $r = r_1$ is a root of multiplicity s of the characteristic polynomial $Z(r)$, then $e^{r_1 t}$, $te^{r_1 t}$, \dots , $t^{s-1}e^{r_1 t}$ are solutions of Eq. (1). This problem extends to n th order equations the method for second order equations given in Problem 22 of Section 3.4. We start from Eq. (2) in the text

$$L[e^{rt}] = e^{rt}Z(r) \tag{i}$$

and differentiate repeatedly with respect to r , setting $r = r_1$ after each differentiation.

- (a) Observe that if r_1 is a root of multiplicity s , then $Z(r) = (r - r_1)^s q(r)$, where $q(r)$ is a polynomial of degree $n - s$ and $q(r_1) \neq 0$. Show that $Z(r_1), Z'(r_1), \dots, Z^{(s-1)}(r_1)$ are all zero, but $Z^{(s)}(r_1) \neq 0$.
- (b) By differentiating Eq. (i) repeatedly with respect to r , show that

$$\begin{aligned} \frac{\partial}{\partial r} L[e^{rt}] &= L \left[\frac{\partial}{\partial r} e^{rt} \right] = L[te^{rt}], \\ &\vdots \\ \frac{\partial^{s-1}}{\partial r^{s-1}} L[e^{rt}] &= L[t^{s-1}e^{rt}] \end{aligned}$$

- (c) Show that $e^{r_1 t}$, $te^{r_1 t}$, \dots , $t^{s-1}e^{r_1 t}$ are solutions of Eq. (1).

Solution

Part (a)

Plug in $r = r_1$ to the formula for $Z(r)$.

$$\begin{aligned} Z(r_1) &= (r_1 - r_1)^s q(r_1) \\ &= 0^s q(r_1) \\ &= 0 \end{aligned}$$

Differentiate $Z(r)$ with respect to r to obtain $Z'(r)$.

$$Z'(r) = s(r - r_1)^{s-1}q(r) + (r - r_1)^s q'(r)$$

Plug in $r = r_1$ to the formula.

$$\begin{aligned} Z'(r_1) &= s(r_1 - r_1)^{s-1}q(r_1) + (r_1 - r_1)^s q'(r_1) \\ &= s(0)^{s-1}q(r_1) + (0)^s q'(r_1) \\ &= 0 \end{aligned}$$

Differentiate $Z'(r)$ with respect to r to obtain $Z''(r)$.

$$Z''(r) = s(s - 1)(r - r_1)^{s-2}q(r) + s(r - r_1)^{s-1}q'(r) + s(r - r_1)^{s-1}q'(r) + (r - r_1)^s q''(r)$$

Plug in $r = r_1$ to the formula.

$$\begin{aligned} Z''(r_1) &= s(s-1)(r_1 - r_1)^{s-2}q(r_1) + s(r_1 - r_1)^{s-1}q'(r_1) + s(r_1 - r_1)^{s-1}q'(r_1) + (r_1 - r_1)^s q''(r_1) \\ &= s(s-1)(0)^{s-2}q(r_1) + s(0)^{s-1}q'(r_1) + s(0)^{s-1}q'(r_1) + (0)^s q''(r_1) \\ &= 0 \\ &\vdots \end{aligned}$$

Differentiate $Z(r)$ $s - 1$ times with respect to r .

$$Z^{(s-1)}(r) = s(s-1)(s-2)\cdots(3)(2)(r-r_1)^{s-(s-1)}q(r) + \text{terms with factors of } r-r_1$$

Plug in $r = r_1$ to the formula.

$$\begin{aligned} Z^{(s-1)}(r_1) &= s(s-1)(s-2)\cdots(3)(2)(r_1 - r_1)^{s-(s-1)}q(r_1) + \text{terms with factors of } r_1 - r_1 \\ &= s(s-1)(s-2)\cdots(3)(2)(0)^1q(r_1) + \text{terms with factors of } 0 \\ &= 0 \end{aligned}$$

Differentiate $Z^{(s-1)}(r)$ once more with respect to r .

$$\begin{aligned} Z^{(s)}(r) &= s(s-1)(s-2)\cdots(3)(2)(1)(r-r_1)^{s-s}q(r) + \text{terms with factors of } r-r_1 \\ &= s!(r-r_1)^0q(r) + \text{terms with factors of } r-r_1 \\ &= s!q(r) + \text{terms with factors of } r-r_1 \end{aligned}$$

Plug in $r = r_1$ to the formula.

$$\begin{aligned} Z^{(s)}(r_1) &= s!q(r_1) + \text{terms with factors of } r_1 - r_1 \\ &= s!q(r_1) + \text{terms with factors of } 0 \\ &= s!q(r_1) \\ &\neq 0 \end{aligned}$$

Part (b)

First rewrite the right side of Eq. (i).

$$\begin{aligned} L[e^{rt}] &= e^{rt}Z(r) \\ &= e^{rt}(a_0r^n + a_1r^{n-1} + \cdots + a_{n-1}r + a_n) \\ &= a_0r^n e^{rt} + a_1r^{n-1}e^{rt} + \cdots + a_{n-1}r e^{rt} + a_n e^{rt} \\ &= a_0 \frac{d^n}{dt^n}(e^{rt}) + a_1 \frac{d^{n-1}}{dt^{n-1}}(e^{rt}) + \cdots + a_{n-1} \frac{d}{dt}(e^{rt}) + a_n e^{rt} \end{aligned}$$

Differentiate both sides m times with respect to r , where $m = 1, 2, \dots, s - 1$.

$$\begin{aligned} \frac{\partial^m}{\partial r^m} L[e^{rt}] &= \frac{\partial^m}{\partial r^m} \left[a_0 \frac{d^n}{dt^n}(e^{rt}) + a_1 \frac{d^{n-1}}{dt^{n-1}}(e^{rt}) + \cdots + a_{n-1} \frac{d}{dt}(e^{rt}) + a_n e^{rt} \right] \\ &= a_0 \frac{\partial^m}{\partial r^m} \frac{d^n}{dt^n}(e^{rt}) + a_1 \frac{\partial^m}{\partial r^m} \frac{d^{n-1}}{dt^{n-1}}(e^{rt}) + \cdots + a_{n-1} \frac{\partial^m}{\partial r^m} \frac{d}{dt}(e^{rt}) + a_n \frac{\partial^m}{\partial r^m} e^{rt} \end{aligned}$$

Since all partial derivatives of e^{rt} are continuous, the mixed derivatives are equal by Clairaut's theorem.

$$\begin{aligned} \frac{\partial^m}{\partial r^m} L[e^{rt}] &= a_0 \frac{d^n}{dt^n} \left(\frac{\partial^m}{\partial r^m} e^{rt} \right) + a_1 \frac{d^{n-1}}{dt^{n-1}} \left(\frac{\partial^m}{\partial r^m} e^{rt} \right) + \cdots + a_{n-1} \frac{d}{dt} \left(\frac{\partial^m}{\partial r^m} e^{rt} \right) + a_n \frac{\partial^m}{\partial r^m} e^{rt} \\ &= a_0 \frac{d^n}{dt^n} (t^m e^{rt}) + a_1 \frac{d^{n-1}}{dt^{n-1}} (t^m e^{rt}) + \cdots + a_{n-1} \frac{d}{dt} (t^m e^{rt}) + a_n (t^m e^{rt}) \\ &= L[t^m e^{rt}] \end{aligned}$$

Part (c)

Eq. (1) in the textbook is

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \cdots + a_{n-1} y' + a_n y = 0. \quad (1)$$

Use the results of part (b) together with Eq. (i) to determine $L[e^{rt}]$, $L[te^{rt}]$, \dots , $L[t^{s-1}e^{rt}]$.

$$\begin{aligned} L[e^{rt}] &= e^{rt} Z(r) & (i) \\ L[te^{rt}] &= \frac{\partial}{\partial r} L[e^{rt}] = \frac{\partial}{\partial r} [e^{rt} Z(r)] = te^{rt} Z(r) + e^{rt} Z'(r) \\ L[t^2 e^{rt}] &= \frac{\partial^2}{\partial r^2} L[e^{rt}] = \frac{\partial^2}{\partial r^2} [e^{rt} Z(r)] = t^2 e^{rt} Z(r) + 2te^{rt} Z'(r) + e^{rt} Z''(r) \\ L[t^3 e^{rt}] &= \frac{\partial^3}{\partial r^3} L[e^{rt}] = \frac{\partial^3}{\partial r^3} [e^{rt} Z(r)] = t^3 e^{rt} Z(r) + 3t^2 e^{rt} Z'(r) + 3te^{rt} Z''(r) + e^{rt} Z'''(r) \\ L[t^4 e^{rt}] &= \frac{\partial^4}{\partial r^4} L[e^{rt}] = \frac{\partial^4}{\partial r^4} [e^{rt} Z(r)] = t^4 e^{rt} Z(r) + 4t^3 e^{rt} Z'(r) + 6t^2 e^{rt} Z''(r) + 4te^{rt} Z'''(r) + e^{rt} Z^{(4)}(r) \\ &\vdots \\ L[t^{s-1} e^{rt}] &= \frac{\partial^{s-1}}{\partial r^{s-1}} L[e^{rt}] = \frac{\partial^{s-1}}{\partial r^{s-1}} [e^{rt} Z(r)] = t^{s-1} e^{rt} Z(r) + \cdots + e^{rt} Z^{(s-1)}(r) \end{aligned}$$

Plugging in $r = r_1$ and using the results from part (a), we see that every right side evaluates to zero.

$$\begin{aligned} L[e^{r_1 t}] &= e^{r_1 t} Z(r_1) = 0 \\ L[te^{r_1 t}] &= te^{r_1 t} Z(r_1) + e^{r_1 t} Z'(r_1) = 0 \\ L[t^2 e^{r_1 t}] &= t^2 e^{r_1 t} Z(r_1) + 2te^{r_1 t} Z'(r_1) + e^{r_1 t} Z''(r_1) = 0 \\ L[t^3 e^{r_1 t}] &= t^3 e^{r_1 t} Z(r_1) + 3t^2 e^{r_1 t} Z'(r_1) + 3te^{r_1 t} Z''(r_1) + e^{r_1 t} Z'''(r_1) = 0 \\ L[t^4 e^{r_1 t}] &= t^4 e^{r_1 t} Z(r_1) + 4t^3 e^{r_1 t} Z'(r_1) + 6t^2 e^{r_1 t} Z''(r_1) + 4te^{r_1 t} Z'''(r_1) + e^{r_1 t} Z^{(4)}(r_1) = 0 \\ &\vdots \\ L[t^{s-1} e^{r_1 t}] &= t^{s-1} e^{r_1 t} Z(r_1) + \cdots + e^{r_1 t} Z^{(s-1)}(r_1) = 0 \end{aligned}$$

Therefore, $e^{r_1 t}$, $te^{r_1 t}$, $t^2 e^{r_1 t}$, \dots , $t^{s-1} e^{r_1 t}$ are solutions to Eq. (1).