

Bonus Identity

$$\nabla [\mathbf{A} \cdot (\mathbf{B} \times \mathbf{r})] = \mathbf{A} \times \mathbf{B}$$

\mathbf{A} and \mathbf{B} are constant vectors, and \mathbf{r} is the position vector.

Proof

$$\begin{aligned} \nabla [\mathbf{A} \cdot (\mathbf{B} \times \mathbf{r})] &= \sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \left\{ \left(\sum_{j=1}^3 \delta_j A_j \right) \cdot \left[\left(\sum_{k=1}^3 \delta_k B_k \right) \times \left(\sum_{l=1}^3 \delta_l x_l \right) \right] \right\} \\ &= \sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \left\{ \left(\sum_{j=1}^3 \delta_j A_j \right) \cdot \left[\sum_{k=1}^3 \sum_{l=1}^3 (\delta_k \times \delta_l) B_k x_l \right] \right\} \\ &= \sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \left[\left(\sum_{j=1}^3 \delta_j A_j \right) \cdot \left(\sum_{k=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 \delta_m \varepsilon_{klm} B_k x_l \right) \right] \\ &= \sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \left[\sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 (\delta_j \cdot \delta_m) \varepsilon_{klm} A_j B_k x_l \right] \\ &= \sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \left(\sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 \delta_{jm} \varepsilon_{klm} A_j B_k x_l \right) \\ &= \sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \left(\sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \varepsilon_{klj} A_j B_k x_l \right) \\ &= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \delta_i \varepsilon_{klj} \frac{\partial}{\partial x_i} A_j B_k x_l \\ &= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \delta_i \varepsilon_{klj} A_j B_k \frac{\partial x_l}{\partial x_i} \\ &= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \delta_i \varepsilon_{klj} A_j B_k \delta_{il} \\ &= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \delta_i \varepsilon_{kij} A_j B_k \\ &= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \delta_i \varepsilon_{jki} A_j B_k \\ &= \sum_{j=1}^3 \sum_{k=1}^3 (\delta_j \times \delta_k) A_j B_k \\ &= \left(\sum_{j=1}^3 \delta_j A_j \right) \times \left(\sum_{k=1}^3 \delta_k B_k \right) = \mathbf{A} \times \mathbf{B} \end{aligned}$$