

Problem 4A.2

Velocity near a moving sphere. A sphere of radius R is falling in creeping flow with a terminal velocity v_∞ through a quiescent fluid of viscosity μ . At what horizontal distance from the sphere does the velocity of the fluid fall to 1% of the terminal velocity of the sphere?

Answer: About 37 diameters

Solution

For a falling sphere in creeping flow (also known as Stokes flow), the following spherical coordinate system was considered in §2.6.

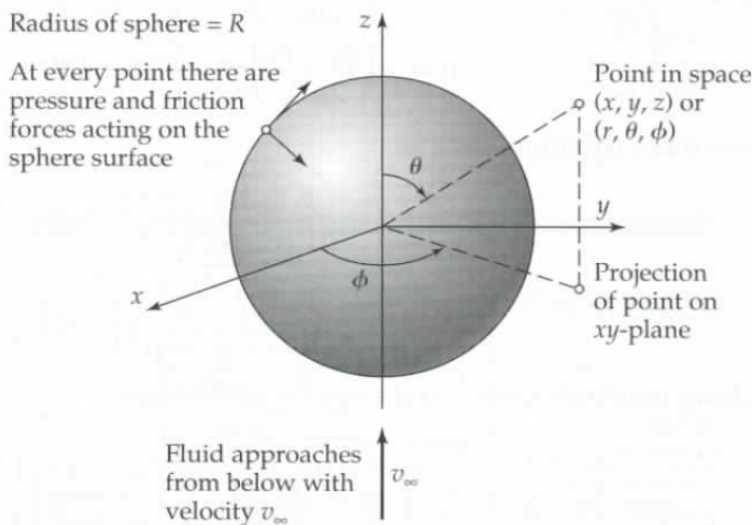


Fig. 2.6-1 Sphere of radius R around which a fluid is flowing. The coordinates r , θ , and ϕ are shown. For more information on spherical coordinates, see Fig. A.8-2.

The components of velocity of the surrounding fluid were found by means of a stream function in Example 4.2-1 to be

$$v_r = v_\infty \left[1 - \frac{3}{2} \left(\frac{R}{r} \right) + \frac{1}{2} \left(\frac{R}{r} \right)^3 \right] \cos \theta$$

$$v_\theta = v_\infty \left[-1 + \frac{3}{4} \left(\frac{R}{r} \right) + \frac{1}{4} \left(\frac{R}{r} \right)^3 \right] \sin \theta$$

$$v_\phi = 0.$$

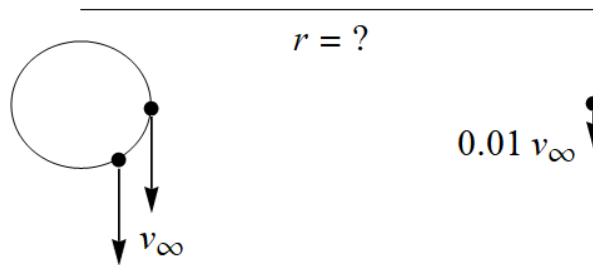
A horizontal distance from the sphere occurs at $\theta = \pi/2$.

$$v_r \left(r, \frac{\pi}{2}, \phi \right) = 0$$

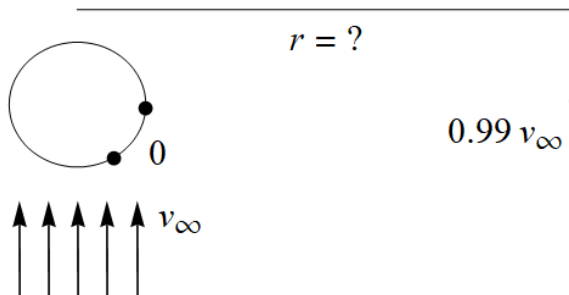
$$v_\theta \left(r, \frac{\pi}{2}, \phi \right) = v_\infty \left[-1 + \frac{3}{4} \left(\frac{R}{r} \right) + \frac{1}{4} \left(\frac{R}{r} \right)^3 \right]$$

$$v_\phi \left(r, \frac{\pi}{2}, \phi \right) = 0$$

The aim in this problem is to find the horizontal distance from the sphere such that the fluid velocity is $0.01v_\infty$ downward. Note that because the fluid is assumed not to slip on the sphere's surface, points on the sphere have a velocity of v_∞ downward.



The previous formulas cannot be applied at the moment because they were derived for a stationary sphere in a fluid flowing upward from the bottom. Add $v_\infty \hat{z}$ to the velocity at every point to not only make the sphere stationary, but also to introduce a flow from the bottom.



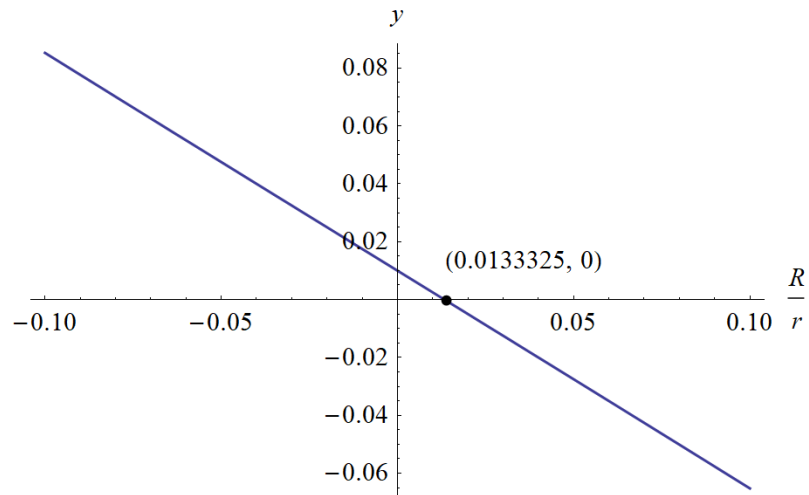
Set $v_\theta = -0.99v_\infty$ and solve this equation for r . The minus sign accounts for the fact that the fluid flows around the sphere in the negative θ -direction.

$$v_\infty \left[-1 + \frac{3}{4} \left(\frac{R}{r} \right) + \frac{1}{4} \left(\frac{R}{r} \right)^3 \right] = -0.99v_\infty$$

$$1 - \frac{3}{4} \left(\frac{R}{r} \right) - \frac{1}{4} \left(\frac{R}{r} \right)^3 = 0.99$$

$$0.01 - \frac{3}{4} \left(\frac{R}{r} \right) - \frac{1}{4} \left(\frac{R}{r} \right)^3 = 0$$

Plot this function on the left side versus R/r and find where it crosses the horizontal axis.



Therefore,

$$\frac{R}{r} \approx 0.0133325 \quad \rightarrow \quad r \approx 75R \approx 37 \text{ diameters.}$$

Here the formulas for the pressure and components of velocity for the flow around a sphere will be derived without using a stream function. For a stationary sphere in a fluid flowing upward from the bottom (illustrated in Fig. 2.6-1), the velocity of the surrounding fluid is assumed to have radial and polar components that both vary with r and θ .

$$\mathbf{v} = v_r(r, \theta)\hat{\mathbf{r}} + v_\theta(r, \theta)\hat{\boldsymbol{\theta}}$$

In addition, the pressure is assumed to vary with r and θ .

$$p = p(r, \theta)$$

One boundary condition is obtained from the assumption that no fluid crosses the spherical surface (that is, it's impermeable), and a second is obtained from the assumption that the fluid does not slip on the spherical surface.

$$\text{Boundary Condition 1: } v_r(R, \theta) = 0$$

$$\text{Boundary Condition 2: } v_\theta(R, \theta) = 0$$

Another two boundary conditions are obtained from the fact that the flow is symmetric about the line which is collinear with the polar axis.

$$\text{Boundary Condition 3: } \frac{\partial v_r}{\partial \theta}(r, 0) = 0$$

$$\text{Boundary Condition 4: } \frac{\partial v_r}{\partial \theta}(r, \pi) = 0$$

Another two boundary conditions are obtained from the fact that the flow is entirely radial at $\theta = 0$ and $\theta = \pi$.

$$\text{Boundary Condition 5: } v_\theta(r, 0) = 0$$

$$\text{Boundary Condition 6: } v_\theta(r, \pi) = 0$$

The equation of continuity results by considering a mass balance over a volume element that the fluid is flowing through. Since the fluid density is assumed to be constant, the equation simplifies to

$$\nabla \cdot \mathbf{v} = 0.$$

Expand the left side in spherical coordinates, using the formula in Appendix B.4 on page 846.

$$\frac{1}{r^2} \frac{\partial}{\partial r}(r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}(v_\theta \sin \theta) + \underbrace{\frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}}_{=0} = 0$$

Multiply both sides by r^2 .

$$\frac{\partial}{\partial r}(r^2 v_r) + \frac{r}{\sin \theta} \frac{\partial}{\partial \theta}(v_\theta \sin \theta) = 0 \quad (1)$$

The equation of motion results by considering a momentum balance over a volume element that the fluid is flowing through. Assuming the fluid viscosity μ is also constant, the equation simplifies to the Navier-Stokes equation.

$$\frac{\partial}{\partial t} \rho \mathbf{v} + \nabla \cdot \rho \mathbf{v} \mathbf{v} = -\nabla p + \mu \nabla^2 \mathbf{v} + \rho \mathbf{g}$$

As this is a vector equation, it actually represents three scalar equations, one for each variable in the chosen coordinate system. From Appendix B.6 on page 848, the Navier-Stokes equation yields the following three scalar equations in spherical coordinates.

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \right) = -\frac{\partial p}{\partial r} + \mu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_r}{\partial \phi^2} \right] + \rho g_r$$

$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta - v_\phi^2 \cot \theta}{r} \right) = -\frac{1}{r} \frac{\partial p}{\partial \theta} + \mu \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\theta}{\partial \phi^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} - \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\phi}{\partial \phi} \right] + \rho g_\theta$$

$$\rho \left(\frac{\partial v_\phi}{\partial t} + v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_\phi v_r + v_\theta v_\phi \cot \theta}{r} \right) = -\frac{1}{r \sin \theta} \frac{\partial p}{\partial \phi} + \mu \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\phi \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2 \sin \theta} \frac{\partial v_r}{\partial \phi} + \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\theta}{\partial \phi} \right] + \rho g_\phi$$

All acceleration terms on each left side are neglected because of the creeping flow assumption. The two relevant equations are as follows.

$$0 = -\frac{\partial p}{\partial r} + \mu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) + \overbrace{\frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_r}{\partial \phi^2}}^{=0} \right] + \rho g_r \quad (2)$$

$$0 = -\frac{1}{r} \frac{\partial p}{\partial \theta} + \mu \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) + \underbrace{\frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\theta}{\partial \phi^2}}_{=0} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} - \underbrace{\frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\phi}{\partial \phi}}_{=0} \right] + \rho g_\theta \quad (3)$$

The system of equations (1), (2), and (3) can be solved for the three unknowns, p , v_r , and v_θ . Multiply both sides of equation (3) by $-r$.

$$0 = -\frac{\partial p}{\partial r} + \mu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) \right] + \rho g_r$$

$$0 = \frac{\partial p}{\partial \theta} + \mu \left[-\frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) - \frac{2}{r} \frac{\partial v_r}{\partial \theta} \right] - \rho g_\theta$$

In this problem gravity points straight down: $\mathbf{g} = -g\hat{\mathbf{z}}$. Write this unit vector in terms of $\hat{\mathbf{r}}$ and $\hat{\boldsymbol{\theta}}$ by using formula A.6-33 on page 828.

$$\mathbf{g} = -g[(\cos \theta)\hat{\mathbf{r}} + (-\sin \theta)\hat{\boldsymbol{\theta}}] = -g(\cos \theta)\hat{\mathbf{r}} + g(\sin \theta)\hat{\boldsymbol{\theta}}$$

We see that $g_r = -g \cos \theta$ and $g_\theta = g \sin \theta$. The previous two equations become

$$\begin{aligned} 0 &= -\frac{\partial p}{\partial r} + \mu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) \right] - \rho g \cos \theta \\ 0 &= \frac{\partial p}{\partial \theta} + \mu \left[-\frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) - \frac{2}{r} \frac{\partial v_r}{\partial \theta} \right] - \rho g r \sin \theta. \end{aligned}$$

Combine the first and last terms on the right side of each equation.

$$\begin{aligned} 0 &= -\frac{\partial}{\partial r} (p + \rho g r \cos \theta) + \mu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) \right] \\ 0 &= \frac{\partial}{\partial \theta} (p + \rho g r \cos \theta) + \mu \left[-\frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) - \frac{2}{r} \frac{\partial v_r}{\partial \theta} \right] \end{aligned}$$

Introduce the modified pressure function $\mathcal{P}(r, \theta) = p(r, \theta) + \rho g r \cos \theta$.

$$0 = -\frac{\partial \mathcal{P}}{\partial r} + \mu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) \right] \quad (4)$$

$$0 = \frac{\partial \mathcal{P}}{\partial \theta} + \mu \left[-\frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) - \frac{2}{r} \frac{\partial v_r}{\partial \theta} \right] \quad (5)$$

Differentiate both sides of the first equation with respect to θ , and differentiate both sides of the second equation with respect to r .

$$\begin{aligned} 0 &= -\frac{\partial^2 \mathcal{P}}{\partial \theta \partial r} + \mu \frac{\partial}{\partial \theta} \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) \right] \\ 0 &= \frac{\partial^2 \mathcal{P}}{\partial r \partial \theta} + \mu \frac{\partial}{\partial r} \left[-\frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) - \frac{2}{r} \frac{\partial v_r}{\partial \theta} \right] \end{aligned}$$

Add the respective sides of each equation in order to eliminate the modified pressure. The mixed derivatives are equal by Clairaut's theorem.

$$0 = \mu \frac{\partial}{\partial \theta} \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) \right] + \mu \frac{\partial}{\partial r} \left[-\frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) - \frac{2}{r} \frac{\partial v_r}{\partial \theta} \right]$$

Divide both sides by μ .

$$0 = \frac{\partial}{\partial \theta} \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) \right] + \frac{\partial}{\partial r} \left[-\frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) - \frac{2}{r} \frac{\partial v_r}{\partial \theta} \right] \quad (6)$$

Equations (1) and (6) together form a system of two equations for v_r and v_θ . Since both PDEs are linear and homogeneous, the method of separation of variables can be applied to get a solution. Assume that v_r and v_θ have product solutions like so: $v_r = Q(r)T(\theta)$ and $v_\theta = \xi(r)\Theta(\theta)$. In particular, based on boundary conditions 3 and 4, we hypothesize that $T(\theta) = \cos \theta$; in addition, based on boundary conditions 5 and 6, we hypothesize that $\Theta(\theta) = \sin \theta$.

$$\begin{aligned} v_r(r, \theta) &= Q(r) \cos \theta \\ v_\theta(r, \theta) &= \xi(r) \sin \theta \end{aligned}$$

Substitute these formulas into equations (1) and (6).

$$\begin{aligned} \frac{\partial}{\partial r} [r^2 Q(r) \cos \theta] + \frac{r}{\sin \theta} \frac{\partial}{\partial \theta} [\xi(r) \sin^2 \theta] &= 0 \\ \frac{\partial}{\partial \theta} \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} [r^2 Q(r) \cos \theta] + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} [Q(r) \cos \theta] \right) \right] \\ + \frac{\partial}{\partial r} \left[-\frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} [\xi(r) \sin \theta] \right) - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} [\xi(r) \sin^2 \theta] \right) - \frac{2}{r} \frac{\partial}{\partial \theta} [Q(r) \cos \theta] \right] &= 0 \end{aligned}$$

Evaluate the derivatives and expand the left sides.

$$\begin{aligned} 2rQ(r) \cos \theta + r^2 Q'(r) \cos \theta + 2r\xi(r) \cos \theta &= 0 \\ -Q''(r) \sin \theta - Q'(r) \frac{4 \sin \theta}{r} - \cancel{Q(r) \frac{2 \sin \theta}{r^2}} + \cancel{Q(r) \frac{2 \sin \theta}{r^2}} \\ -r\xi'''(r) \sin \theta - 3\xi''(r) \sin \theta + \xi'(r) \frac{2 \sin \theta}{r} - \xi(r) \frac{2 \sin \theta}{r^2} + Q'(r) \frac{2 \sin \theta}{r} - Q(r) \frac{2 \sin \theta}{r^2} &= 0 \end{aligned}$$

Divide both sides of the first equation by $r \cos \theta$, and divide both sides of the second equation by $\sin \theta$.

$$\begin{aligned} 2Q(r) + rQ'(r) + 2\xi(r) &= 0 \\ -Q''(r) - Q'(r) \frac{2}{r} - Q(r) \frac{2}{r^2} - r\xi'''(r) - 3\xi''(r) + \xi'(r) \frac{2}{r} - \xi(r) \frac{2}{r^2} &= 0 \end{aligned}$$

Solve the first equation for $\xi(r)$

$$\xi(r) = -Q(r) - \frac{r}{2} Q'(r) \quad (7)$$

and then substitute it into the second equation.

$$\begin{aligned} -Q''(r) - Q'(r) \frac{2}{r} - Q(r) \frac{2}{r^2} - r \left[-Q(r) - \frac{r}{2} Q'(r) \right]''' - 3 \left[-Q(r) - \frac{r}{2} Q'(r) \right]'' \\ + \left[-Q(r) - \frac{r}{2} Q'(r) \right]' \frac{2}{r} - \left[-Q(r) - \frac{r}{2} Q'(r) \right] \frac{2}{r^2} &= 0 \end{aligned}$$

Simplify the left side.

$$\frac{1}{2} r^2 Q'''' + 4rQ''' + 4Q'' - \frac{4}{r} Q' = 0$$

Multiply both sides by $2r^2$.

$$r^4 Q'''' + 8r^3 Q''' + 8r^2 Q'' - 8rQ' = 0$$

This is a homogeneous equidimensional ODE, so its solution is of the form $Q = r^m$.

$$\begin{aligned} Q = r^m \quad \rightarrow \quad Q' = mr^{m-1} \quad \rightarrow \quad Q'' = m(m-1)r^{m-2} \quad \rightarrow \quad Q''' = m(m-1)(m-2)r^{m-3} \\ \rightarrow \quad Q'''' = m(m-1)(m-2)(m-3)r^{m-4} \end{aligned}$$

Substitute these formulas into the ODE.

$$\begin{aligned} r^4 m(m-1)(m-2)(m-3)r^{m-4} + 8r^3 m(m-1)(m-2)r^{m-3} + 8r^2 m(m-1)r^{m-2} - 8mr^{m-1} &= 0 \\ m(m-1)(m-2)(m-3)r^m + 8m(m-1)(m-2)r^m + 8m(m-1)r^m - 8mr^m &= 0 \end{aligned}$$

Divide both sides by r^m .

$$m(m-1)(m-2)(m-3) + 8m(m-1)(m-2) + 8m(m-1) - 8m = 0$$

Expand the left side.

$$m^4 + 2m^3 - 5m^2 - 6m = 0$$

$$m(m+3)(m+1)(m-2) = 0$$

$$m = \{-3, -1, 0, 2\}$$

Four solutions to the ODE are $Q = r^{-3}$ and $Q = r^{-1}$ and $Q = r^0 = 1$ and $Q = r^2$. By the principle of superposition, the general solution to the ODE is a linear combination of these four.

$$Q(r) = C_1 r^{-3} + C_2 r^{-1} + C_3 + C_4 r^2$$

Substitute this formula for Q into equation (7) to get ξ .

$$\xi(r) = \frac{C_1}{2} r^{-3} - \frac{C_2}{2} r^{-1} - C_3 - 2C_4 r^2$$

Therefore, since $v_r(r, \theta) = Q(r) \cos \theta$ and $v_\theta(r, \theta) = \xi(r) \sin \theta$,

$$v_r(r, \theta) = \left(\frac{C_1}{r^3} + \frac{C_2}{r} + C_3 + C_4 r^2 \right) \cos \theta$$

$$v_\theta(r, \theta) = \left(\frac{C_1}{2r^3} - \frac{C_2}{2r} - C_3 - 2C_4 r^2 \right) \sin \theta.$$

Now plug these formulas into equations (4) and (5) to get the modified pressure.

$$0 = -\frac{\partial \mathcal{P}}{\partial r} + 2\mu \left(5C_4 - \frac{C_2}{r^3} \right) \cos \theta$$

$$0 = \frac{\partial \mathcal{P}}{\partial \theta} + \mu \left(\frac{C_2}{r^2} + 10C_4 r \right) \sin \theta$$

Solve for the derivatives.

$$\frac{\partial \mathcal{P}}{\partial r} = 2\mu \left(5C_4 - \frac{C_2}{r^3} \right) \cos \theta$$

$$\frac{\partial \mathcal{P}}{\partial \theta} = -\mu \left(\frac{C_2}{r^2} + 10C_4 r \right) \sin \theta$$

Integrate both sides of the second equation partially with respect to θ to get \mathcal{P} .

$$\mathcal{P}(r, \theta) = \mu \left(\frac{C_2}{r^2} + 10C_4 r \right) \cos \theta + f(r)$$

Differentiate both sides with respect to r .

$$\frac{\partial \mathcal{P}}{\partial r} = \mu \left(-\frac{2C_2}{r^3} + 10C_4 \right) \cos \theta + f'(r)$$

Comparing this to the previous equation for $\partial \mathcal{P} / \partial r$, we see that

$$f'(r) = 0.$$

Integrate both sides with respect to r .

$$f(r) = \mathcal{P}_\infty$$

The modified pressure is then

$$\mathcal{P}(r, \theta) = \mu \left(\frac{C_2}{r^2} + 10C_4r \right) \cos \theta + \mathcal{P}_\infty.$$

We require that $\mathcal{P} = \mathcal{P}_\infty$ in the limit as $r \rightarrow \infty$: $C_4 = 0$.

$$\mathcal{P}(r, \theta) = \mu \frac{C_2}{r^2} \cos \theta + \mathcal{P}_\infty$$

Therefore, since $p(r, \theta) = \mathcal{P}(r, \theta) - \rho gr \cos \theta$,

$$p(r, \theta) = \mathcal{P}_\infty - \rho gr \cos \theta + \mu \frac{C_2}{r^2} \cos \theta.$$

$C_4 = 0$, so the velocity components become

$$v_r(r, \theta) = \left(\frac{C_1}{r^3} + \frac{C_2}{r} + C_3 \right) \cos \theta$$

$$v_\theta(r, \theta) = \left(\frac{C_1}{2r^3} - \frac{C_2}{2r} - C_3 \right) \sin \theta.$$

Apply boundary conditions 1 and 2 to determine C_1 and C_3 .

$$v_r(R, \theta) = \left(\frac{C_1}{R^3} + \frac{C_2}{R} + C_3 \right) \cos \theta = 0$$

$$v_\theta(R, \theta) = \left(\frac{C_1}{2R^3} - \frac{C_2}{2R} - C_3 \right) \sin \theta = 0$$

Solving this system of equations yields

$$C_1 = -\frac{C_2 R^2}{3} \quad \text{and} \quad C_3 = -\frac{2C_2}{3R}.$$

As a result, the velocity components become

$$v_r(r, \theta) = \left(-\frac{C_2 R^2}{3r^3} + \frac{C_2}{r} - \frac{2C_2}{3R} \right) \cos \theta$$

$$v_\theta(r, \theta) = \left(-\frac{C_2 R^2}{6r^3} - \frac{C_2}{2r} + \frac{2C_2}{3R} \right) \sin \theta,$$

or after simplifying,

$$v_r(r, \theta) = -\frac{2C_2}{3R} \left[1 - \frac{3}{2} \left(\frac{R}{r} \right) + \frac{1}{2} \left(\frac{R}{r} \right)^3 \right] \cos \theta$$

$$v_\theta(r, \theta) = -\frac{2C_2}{3R} \left[-1 + \frac{3}{4} \left(\frac{R}{r} \right) + \frac{1}{4} \left(\frac{R}{r} \right)^3 \right] \sin \theta.$$

The boxed formulas in §2.6 are obtained by setting $\mathcal{P}_\infty = p_0$, noting that $z = r \cos \theta$, and using one final boundary condition to determine that $-2C_2/(3R) = v_\infty$.