

## Problem 26

In each of Problems 24 through 27, the eigenvalues and eigenvectors of a matrix  $\mathbf{A}$  are given. Consider the corresponding system  $\mathbf{x}' = \mathbf{A}\mathbf{x}$ .

- Sketch a phase portrait of the system.
- Sketch the trajectory passing through the initial point  $(2, 3)$ .
- For the trajectory in part (b), sketch the graphs of  $x_1$  versus  $t$  and of  $x_2$  versus  $t$  on the same set of axes.

$$r_1 = -1, \quad \boldsymbol{\xi}^{(1)} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}; \quad r_2 = 2, \quad \boldsymbol{\xi}^{(2)} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

### Solution

Because this is a constant-coefficient homogeneous linear system, it's expected to have solutions of the form  $\mathbf{x} = e^{\lambda t}\boldsymbol{\xi}$ , where  $\boldsymbol{\xi}$  has constant elements.

$$\lambda e^{\lambda t}\boldsymbol{\xi} = \mathbf{A}e^{\lambda t}\boldsymbol{\xi}$$

Divide both sides by  $e^{\lambda t}$ .

$$\lambda\boldsymbol{\xi} = \mathbf{A}\boldsymbol{\xi}$$

This is now an eigenvalue problem.

$$(\mathbf{A} - \lambda\mathbf{I})\boldsymbol{\xi} = \mathbf{0}$$

$$\begin{pmatrix} A_{11} - \lambda & A_{12} \\ A_{21} & A_{22} - \lambda \end{pmatrix} \boldsymbol{\xi} = \mathbf{0}$$

The elements of  $\mathbf{A}$  can be deduced from the provided eigenvalues and eigenvectors.

$$\begin{aligned} \begin{pmatrix} A_{11} - \lambda_1 & A_{12} \\ A_{21} & A_{22} - \lambda_1 \end{pmatrix} \boldsymbol{\xi}_1 &= \mathbf{0} & \begin{pmatrix} A_{11} - \lambda_2 & A_{12} \\ A_{21} & A_{22} - \lambda_2 \end{pmatrix} \boldsymbol{\xi}_2 &= \mathbf{0} \\ \begin{pmatrix} A_{11} + 1 & A_{12} \\ A_{21} & A_{22} + 1 \end{pmatrix} \begin{pmatrix} -1 \\ 2 \end{pmatrix} &= \mathbf{0} & \begin{pmatrix} A_{11} - 2 & A_{12} \\ A_{21} & A_{22} - 2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} &= \mathbf{0} \\ \left. \begin{aligned} -A_{11} - 1 + 2A_{12} &= 0 \\ -A_{21} + 2A_{22} + 2 &= 0 \end{aligned} \right\} & & \left. \begin{aligned} A_{11} - 2 + 2A_{12} &= 0 \\ A_{21} + 2A_{22} - 4 &= 0 \end{aligned} \right\} \end{aligned}$$

Solve these four equations for the matrix elements.

$$A_{11} = \frac{1}{2} \quad \text{and} \quad A_{12} = \frac{3}{4} \quad \text{and} \quad A_{21} = 3 \quad \text{and} \quad A_{22} = \frac{1}{2}$$

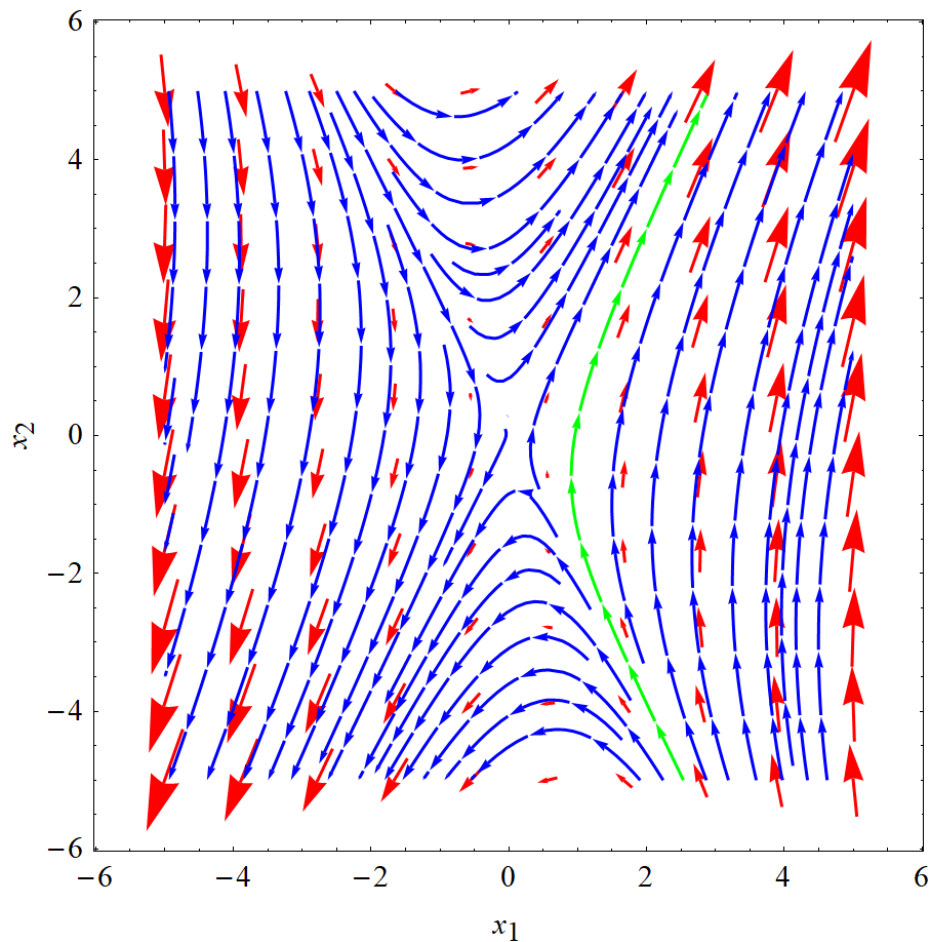
As a result, the system of ODEs is

$$\begin{pmatrix} x_1' \\ x_2' \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{3}{4} \\ 3 & \frac{1}{2} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2}x_1 + \frac{3}{4}x_2 \\ 3x_1 + \frac{1}{2}x_2 \end{pmatrix}.$$

The direction field, the red two-dimensional vector field

$$\left\langle \frac{1}{2}x_1 + \frac{3}{4}x_2, 3x_1 + \frac{1}{2}x_2 \right\rangle,$$

and phase portrait (blue streamlines) of the system can now be drawn.



The trajectory passing through  $(2, 3)$  is shown in green. Use the principle of superposition to get the general solution to the system of ODEs.

$$\begin{aligned} \mathbf{x} &= C_1 e^{\lambda_1 t} \xi_1 + C_2 e^{\lambda_2 t} \xi_2 \\ &= C_1 e^{-t} \begin{pmatrix} -1 \\ 2 \end{pmatrix} + C_2 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} \end{aligned}$$

Determine  $C_1$  and  $C_2$  for this special trajectory.

$$\mathbf{x}(0) = C_1 \begin{pmatrix} -1 \\ 2 \end{pmatrix} + C_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

Write the implied system of equations.

$$\begin{aligned} -C_1 + C_2 &= 2 \\ 2C_1 + 2C_2 &= 3 \end{aligned}$$

Solve for  $C_1$  and  $C_2$ .

$$C_1 = -\frac{1}{4} \quad \text{and} \quad C_2 = \frac{7}{4}$$

Consequently, the solution is

$$\mathbf{x} = -\frac{1}{4}e^{-t} \begin{pmatrix} -1 \\ 2 \end{pmatrix} + \frac{7}{4}e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} \frac{1}{4}e^{-t} + \frac{7}{4}e^{2t} \\ -\frac{1}{2}e^{-t} + \frac{7}{2}e^{2t} \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}.$$

The graph of  $x_1$  and  $x_2$  versus  $t$  is shown below.

