

Problem 1.61

Although the gradient, divergence, and curl theorems are the fundamental integral theorems of vector calculus, it is possible to derive a number of corollaries from them. Show the following:

- (a) $\int_V (\nabla T) d\tau = \oint_S T d\mathbf{a}$. [*Hint:* Let $\mathbf{v} = \mathbf{c}T$, where \mathbf{c} is a constant vector, in the divergence theorem; use the product rules.]
- (b) $\int_V (\nabla \times \mathbf{v}) d\tau = -\oint_S \mathbf{v} \times d\mathbf{a}$. [*Hint:* Replace \mathbf{v} by $(\mathbf{v} \times \mathbf{c})$ in the divergence theorem.]
- (c) $\int_V [T\nabla^2 U + (\nabla T) \cdot (\nabla U)] d\tau = \oint_S (T\nabla U) \cdot d\mathbf{a}$. [*Hint:* Let $\mathbf{v} = T\nabla U$ in the divergence theorem.]
- (d) $\int_V (T\nabla^2 U - U\nabla^2 T) d\tau = \oint_S (T\nabla U - U\nabla T) \cdot d\mathbf{a}$. [*Comment:* This is sometimes called **Green's second identity**; it follows from (c), which is known as **Green's identity**.]
- (e) $\int_S \nabla T \times d\mathbf{a} = -\oint_P T d\mathbf{l}$. [*Hint:* Let $\mathbf{v} = \mathbf{c}T$ in Stokes' theorem.]
- (f) $\int_S [(d\mathbf{a} \times \nabla) \times \mathbf{v}] = -\oint_P \mathbf{v} \times d\mathbf{l}$. [*Hint:* Replace \mathbf{v} by $(\mathbf{v} \times \mathbf{c})$ in Stokes' theorem.]

[**TYPO: This is Green's first identity.**]

Solution

The divergence theorem (or Gauss's theorem) relates the volume integral of $\nabla \cdot \mathbf{v}$ to a closed surface integral.

$$\iiint_D \nabla \cdot \mathbf{v} dV = \oint_{\text{bdy } D} \mathbf{v} \cdot d\mathbf{S}$$

On the other hand, Stokes's theorem relates the integral of a curl over an open surface to a closed loop integral over that surface's boundary line.

$$\iint_S (\nabla \times \mathbf{v}) \cdot d\mathbf{S} = \oint_{\text{bdy } S} \mathbf{v} \cdot d\mathbf{l}$$

Part (a)

Begin with the divergence theorem, let $\mathbf{v} = \mathbf{c}T$ in which \mathbf{c} is constant, and use Identity 5 from inside the front cover.

$$\begin{aligned} \iiint_D \nabla \cdot \mathbf{v} dV &= \oint_{\text{bdy } D} \mathbf{v} \cdot d\mathbf{S} \\ \iiint_D \nabla \cdot (\mathbf{c}T) dV &= \oint_{\text{bdy } D} (\mathbf{c}T) \cdot d\mathbf{S} \\ \iiint_D [T \underbrace{(\nabla \cdot \mathbf{c})}_{=0} + \mathbf{c} \cdot (\nabla T)] dV &= \mathbf{c} \cdot \oint_{\text{bdy } D} T d\mathbf{S} \\ \mathbf{c} \cdot \iiint_D \nabla T dV &= \mathbf{c} \cdot \oint_{\text{bdy } D} T d\mathbf{S} \end{aligned}$$

Therefore,

$$\iiint_D \nabla T \, dV = \oint_{\text{bdy } D} T \, d\mathbf{S}.$$

Part (b)

Begin with the divergence theorem, let $\mathbf{v} = \mathbf{u} \times \mathbf{c}$ in which \mathbf{c} is constant, use Identity 6 on the left, and use Identity 1 on the right.

$$\begin{aligned} \iiint_D \nabla \cdot \mathbf{v} \, dV &= \oint_{\text{bdy } D} \mathbf{v} \cdot d\mathbf{S} \\ \iiint_D \nabla \cdot (\mathbf{u} \times \mathbf{c}) \, dV &= \oint_{\text{bdy } D} (\mathbf{u} \times \mathbf{c}) \cdot d\mathbf{S} \\ \iiint_D [\mathbf{c} \cdot (\nabla \times \mathbf{u}) - \underbrace{\mathbf{u} \cdot (\nabla \times \mathbf{c})}_{=0}] \, dV &= \oint_{\text{bdy } D} \mathbf{c} \cdot (d\mathbf{S} \times \mathbf{u}) \\ \mathbf{c} \cdot \iiint_D (\nabla \times \mathbf{u}) \, dV &= \mathbf{c} \cdot \oint_{\text{bdy } D} (-\mathbf{u} \times d\mathbf{S}) \end{aligned}$$

Therefore,

$$\iiint_D (\nabla \times \mathbf{u}) \, dV = - \oint_{\text{bdy } D} \mathbf{u} \times d\mathbf{S}.$$

Part (c)

Begin with the divergence theorem, let $\mathbf{v} = T\nabla U$ in which T and U are any two scalar differentiable functions defined in the volume D , and use Identity 5 on the left side.

$$\begin{aligned} \iiint_D \nabla \cdot \mathbf{v} \, dV &= \oint_{\text{bdy } D} \mathbf{v} \cdot d\mathbf{S} \\ \iiint_D \nabla \cdot (T\nabla U) \, dV &= \oint_{\text{bdy } D} (T\nabla U) \cdot d\mathbf{S} \\ \iiint_D [T(\nabla \cdot \nabla U) + (\nabla U) \cdot (\nabla T)] \, dV &= \oint_{\text{bdy } D} (T\nabla U) \cdot d\mathbf{S} \end{aligned}$$

Therefore,

$$\iiint_D [T\nabla^2 U + (\nabla T) \cdot (\nabla U)] \, dV = \oint_{\text{bdy } D} (T\nabla U) \cdot d\mathbf{S}.$$

This is Green's first identity.

Part (d)

Green's first identity states that for any two functions, U and T ,

$$\iiint_D [T\nabla^2 U + (\nabla T) \cdot (\nabla U)] dV = \oiint_{\text{bdy } D} (T\nabla U) \cdot d\mathbf{S}. \quad (1)$$

It holds even if T and U are interchanged.

$$\iiint_D [U\nabla^2 T + (\nabla U) \cdot (\nabla T)] dV = \oiint_{\text{bdy } D} (U\nabla T) \cdot d\mathbf{S} \quad (2)$$

Subtract the respective sides of equation (2) from those of equation (1).

$$\begin{aligned} \iiint_D [T\nabla^2 U + (\nabla T) \cdot (\nabla U)] dV - \iiint_D [U\nabla^2 T + (\nabla U) \cdot (\nabla T)] dV &= \oiint_{\text{bdy } D} (T\nabla U) \cdot d\mathbf{S} - \oiint_{\text{bdy } D} (U\nabla T) \cdot d\mathbf{S} \\ \iiint_D [T\nabla^2 U + \cancel{(\nabla T) \cdot (\nabla U)} - U\nabla^2 T - \cancel{(\nabla U) \cdot (\nabla T)}] dV &= \oiint_{\text{bdy } D} (T\nabla U - U\nabla T) \cdot d\mathbf{S} \end{aligned}$$

Therefore,

$$\iiint_D (T\nabla^2 U - U\nabla^2 T) dV = \oiint_{\text{bdy } D} (T\nabla U - U\nabla T) \cdot d\mathbf{S}.$$

This is Green's second identity.

Part (e)

Begin with Stokes's theorem, let $\mathbf{v} = \mathbf{c}T$ in which \mathbf{c} is constant, and use Identity 7 followed by Identity 1 on the left side.

$$\begin{aligned} \iint_S (\nabla \times \mathbf{v}) \cdot d\mathbf{S} &= \oint_{\text{bdy } S} \mathbf{v} \cdot d\mathbf{l} \\ \iint_S [\nabla \times (\mathbf{c}T)] \cdot d\mathbf{S} &= \oint_{\text{bdy } S} (\mathbf{c}T) \cdot d\mathbf{l} \\ \iint_S [T \underbrace{(\nabla \times \mathbf{c})}_{=0} - \mathbf{c} \times (\nabla T)] \cdot d\mathbf{S} &= \mathbf{c} \cdot \oint_{\text{bdy } S} T d\mathbf{l} \\ - \iint_S \mathbf{c} \cdot (\nabla T \times d\mathbf{S}) &= \mathbf{c} \cdot \oint_{\text{bdy } S} T d\mathbf{l} \\ \mathbf{c} \cdot \iint_S (\nabla T \times d\mathbf{S}) &= \mathbf{c} \cdot \oint_{\text{bdy } S} (-T) d\mathbf{l} \end{aligned}$$

Therefore,

$$\iint_S \nabla T \times d\mathbf{S} = - \oint_{\text{bdy } S} T d\mathbf{l}.$$

Part (f)

Begin with Stokes's theorem.

$$\iint_S (\nabla \times \mathbf{v}) \cdot d\mathbf{S} = \oint_{\text{bdy } S} \mathbf{v} \cdot d\mathbf{l}$$

Let $\mathbf{v} = \mathbf{u} \times \mathbf{c}$.

$$\iint_S [\nabla \times (\mathbf{u} \times \mathbf{c})] \cdot d\mathbf{S} = \oint_{\text{bdy } S} (\mathbf{u} \times \mathbf{c}) \cdot d\mathbf{l}$$

Use Identity 1 inside the front cover to rewrite the integral on the right side.

$$\begin{aligned} \iint_S [\nabla \times (\mathbf{u} \times \mathbf{c})] \cdot d\mathbf{S} &= \oint_{\text{bdy } S} (d\mathbf{l} \times \mathbf{u}) \cdot \mathbf{c} \\ &= \oint_{\text{bdy } S} (-\mathbf{u} \times d\mathbf{l}) \cdot \mathbf{c} \end{aligned} \quad (3)$$

Now rewrite the integrand on the left side.

$$\begin{aligned} [\nabla \times (\mathbf{u} \times \mathbf{c})] \cdot d\mathbf{S} &= \left\{ \left(\sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \right) \times \left[\left(\sum_{j=1}^3 \delta_j u_j \right) \times \left(\sum_{k=1}^3 \delta_k c_k \right) \right] \right\} \cdot \left(\sum_{l=1}^3 \delta_l dS_l \right) \\ &= \left\{ \left(\sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \right) \times \left[\sum_{j=1}^3 \sum_{k=1}^3 (\delta_j \times \delta_k) u_j c_k \right] \right\} \cdot \left(\sum_{l=1}^3 \delta_l dS_l \right) \\ &= \left[\left(\sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \right) \times \left(\sum_{j=1}^3 \sum_{k=1}^3 \sum_{m=1}^3 \delta_m \varepsilon_{mjk} u_j c_k \right) \right] \cdot \left(\sum_{l=1}^3 \delta_l dS_l \right) \\ &= \left[\sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{m=1}^3 (\delta_i \times \delta_m) \varepsilon_{mjk} \frac{\partial}{\partial x_i} (u_j c_k) \right] \cdot \left(\sum_{l=1}^3 \delta_l dS_l \right) \\ &= \left[\sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{m=1}^3 \sum_{n=1}^3 \delta_n \varepsilon_{nim} \varepsilon_{mjk} c_k \frac{\partial u_j}{\partial x_i} \right] \cdot \left(\sum_{l=1}^3 \delta_l dS_l \right) \\ &= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 \sum_{n=1}^3 (\delta_n \cdot \delta_l) \varepsilon_{nim} \varepsilon_{mjk} c_k \frac{\partial u_j}{\partial x_i} dS_l \end{aligned}$$

Continue the simplification.

$$\begin{aligned}
[\nabla \times (\mathbf{u} \times \mathbf{c})] \cdot d\mathbf{S} &= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 \sum_{n=1}^3 \delta_{nl} \varepsilon_{nim} \varepsilon_{mjk} c_k \frac{\partial u_j}{\partial x_i} dS_l \\
&= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 \varepsilon_{lim} \varepsilon_{mjk} c_k \frac{\partial u_j}{\partial x_i} dS_l \\
&= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 \sum_{n=1}^3 \delta_{kn} \varepsilon_{lim} \varepsilon_{mjk} c_n \frac{\partial u_j}{\partial x_i} dS_l \\
&= \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 \sum_{n=1}^3 (\delta_k \cdot \delta_n) \varepsilon_{lim} \varepsilon_{mjk} c_n \frac{\partial u_j}{\partial x_i} dS_l \\
&= \left(\sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 \delta_k \varepsilon_{lim} \varepsilon_{mjk} \frac{\partial u_j}{\partial x_i} dS_l \right) \cdot \left(\sum_{n=1}^3 \delta_n c_n \right) \\
&= \left[\sum_{i=1}^3 \sum_{j=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 (\delta_m \times \delta_j) \varepsilon_{lim} \frac{\partial u_j}{\partial x_i} dS_l \right] \cdot \left(\sum_{n=1}^3 \delta_n c_n \right) \\
&= \left[\left(\sum_{i=1}^3 \sum_{l=1}^3 \sum_{m=1}^3 \delta_m \varepsilon_{lim} dS_l \frac{\partial}{\partial x_i} \right) \times \left(\sum_{j=1}^3 \delta_j u_j \right) \right] \cdot \left(\sum_{n=1}^3 \delta_n c_n \right) \\
&= \left\{ \left[\sum_{i=1}^3 \sum_{l=1}^3 (\delta_l \times \delta_i) dS_l \frac{\partial}{\partial x_i} \right] \times \left(\sum_{j=1}^3 \delta_j u_j \right) \right\} \cdot \left(\sum_{n=1}^3 \delta_n c_n \right) \\
&= \left\{ \left[\left(\sum_{l=1}^3 \delta_l dS_l \right) \times \left(\sum_{i=1}^3 \delta_i \frac{\partial}{\partial x_i} \right) \right] \times \left(\sum_{j=1}^3 \delta_j u_j \right) \right\} \cdot \left(\sum_{n=1}^3 \delta_n c_n \right) \\
&= [(d\mathbf{S} \times \nabla) \times \mathbf{u}] \cdot \mathbf{c}
\end{aligned}$$

As a result, equation (3) becomes

$$\iint_S [(d\mathbf{S} \times \nabla) \times \mathbf{u}] \cdot \mathbf{c} = \oint_{\text{bdy } S} (-\mathbf{u} \times d\mathbf{l}) \cdot \mathbf{c}.$$

Since \mathbf{c} is a constant vector, it can be brought outside the integral.

$$\left[\iint_S (d\mathbf{S} \times \nabla) \times \mathbf{u} \right] \cdot \mathbf{c} = \left(- \oint_{\text{bdy } S} \mathbf{u} \times d\mathbf{l} \right) \cdot \mathbf{c}$$

Therefore,

$$\iint_S (d\mathbf{S} \times \nabla) \times \mathbf{u} = - \oint_{\text{bdy } S} \mathbf{u} \times d\mathbf{l}.$$