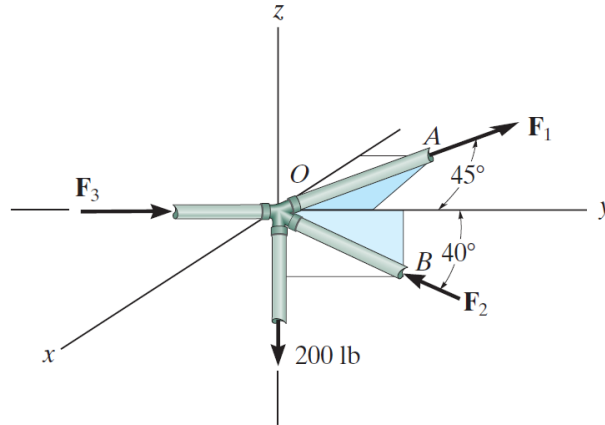


Problem R3-5

The joint of a space frame is subjected to four member forces. Member OA lies in the x - y plane and member OB lies in the y - z plane. Determine the force acting in each of the members required for equilibrium of the joint.



Prob. R3-5

Solution

Begin by writing each of the force vectors in component form.

$$\mathbf{F}_1 = F_1 \langle -\sin 45^\circ, \cos 45^\circ, 0 \rangle$$

$$\mathbf{F}_2 = F_2 \langle 0, -\cos 40^\circ, \sin 40^\circ \rangle$$

$$\mathbf{F}_3 = F_3 \langle 0, 1, 0 \rangle$$

$$\mathbf{F} = 200 \langle 0, 0, -1 \rangle \text{ lb}$$

In order for the joint to be in equilibrium, the sum of the forces must be zero.

$$\mathbf{F}_1 + \mathbf{F}_2 + \mathbf{F}_3 + \mathbf{F} = \mathbf{0}$$

$$F_1 \langle -\sin 45^\circ, \cos 45^\circ, 0 \rangle + F_2 \langle 0, -\cos 40^\circ, \sin 40^\circ \rangle + F_3 \langle 0, 1, 0 \rangle + 200 \langle 0, 0, -1 \rangle \text{ lb} = \mathbf{0}$$

$$\langle -F_1 \sin 45^\circ, F_1 \cos 45^\circ - F_2 \cos 40^\circ + F_3, F_2 \sin 40^\circ - 200 \rangle = \langle 0, 0, 0 \rangle$$

Match the components to get a system of equations and then solve it.

$$\left. \begin{aligned} -F_1 \sin 45^\circ &= 0 \\ F_1 \cos 45^\circ - F_2 \cos 40^\circ + F_3 &= 0 \\ F_2 \sin 40^\circ - 200 &= 0 \end{aligned} \right\} \Rightarrow \begin{cases} F_1 = 0 \text{ lb} \\ F_2 \approx 311 \text{ lb} \\ F_3 \approx 238 \text{ lb} \end{cases}$$